

Learning to reflect

10th International Conference on Lévy Processes – Mannheim 2022

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18 July 2022

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Optimal control for Lévy processes

- ξ upward regular Lévy process on \mathbb{R} , $\mathbb{E}^0[\xi_1] \in (0, \infty)$
- for impulse controls $S = (\tau_n, \zeta_n)_{n \in \mathbb{N}}$

$$\xi_t^S = \xi_t - \sum_{n: \tau_n \leq t} (\xi_{\tau_n, -}^S - \zeta_n)$$

and for a given value function γ solve

$$v^* := \sup_S \liminf_{T \rightarrow \infty} \frac{1}{T} \mathbb{E}^x \left[\sum_{n: \tau_n \leq T} (\gamma(\xi_{\tau_n, -}^S) - \gamma(\zeta_n)) \right]$$

Solution for known dynamics

- essential process determining optimal solution: **ascending ladder height process** $H_t = \xi_{L_t^{-1}}$, where $(L_t)_{t \geq 0}$ is **local time at supremum** of ξ
- Reason: for scaling of L s.t. $\mathbb{E}^0[\xi_1] = \mathbb{E}^0[H_1]$ the long term average reward when **reflecting** in x is given by

$$\mathcal{A}_H \gamma(x) = \lim_{\varepsilon \downarrow 0} \frac{\mathbb{E}^x[\gamma(\xi_{T_{x+\varepsilon}})] - \gamma(x)}{\mathbb{E}^x[T_{x+\varepsilon}]}, \quad T_y := \inf\{t \geq 0 : \xi_t > y\}.$$

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Theorem (Christensen, Sohr (2020))

Let $f := \mathcal{A}_H \gamma$ be unimodal with maximizer θ^* (+ technical assumptions). Then $v^* = f(\theta^*)$ and reflecting in θ^* is optimal.

1. Construct **nonparametric estimator** \hat{f}_T of $f = \mathcal{A}_H \gamma$ given data $(\xi_t)_{t \in [0, T]}$

Data-driven strategy

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3. Analyze **sup-norm estimation rates** of \hat{f}_T to determine regret of the strategy, since for $\theta^* \in K$

$$\mathbb{E}^0[f(\theta^*) - f(\hat{\theta}_T)] \leq 2\mathbb{E}^0[\|\hat{f}_T - f\|_{L^\infty(K^\circ)}].$$

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Statistical challenge

How can we build an estimator of $\mathcal{A}_H\gamma$ although local time L **cannot be observed**?

Construction of a spatial estimator

- Integration by parts reveals

$$\mathcal{A}_H\gamma(x) = d_H\gamma'(x) + \int_{0+}^{\infty} (\gamma(x+y) - \gamma(x)) \Pi_H(dy) = \int_0^{\infty} \eta\gamma'(x+y) \mu(dy),$$

where $\eta = \mathbb{E}^0[\xi_1]$ and

$$\mu(dy) = \frac{1}{\mathbb{E}^0[\xi_1]} \left(d_H\delta_0(dy) + \Pi_H((y, \infty)) dy \mathbf{1}_{(0, \infty)}(y) \right), \quad y \geq 0.$$

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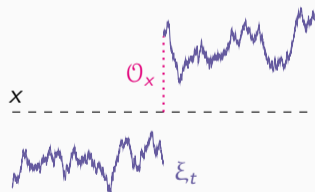
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$$\mathcal{O}_x = \xi_{T_x} - x, \quad x \geq 0,$$

be the **overshoot** of ξ over a level x .



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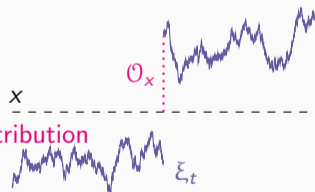
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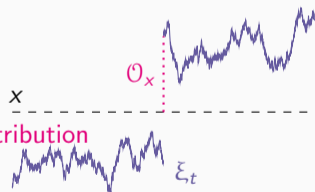
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- $(\mathcal{O}_x)_{x \geq 0}$ is a \mathbb{R}_+ -valued Feller process and μ is its **invariant distribution**
- natural (spatial) estimator

$$\tilde{f}_Y(x) = \frac{1}{Y} \int_0^Y \eta \gamma'(x + \mathcal{O}_y) dy,$$

given data $(\xi_{T_y})_{y \in [0, Y]}$.



From overshoots to path integrals of Markov processes

Note that

$$\mathbb{E}^0[\|\tilde{f}_Y - f\|_{L^\infty(D)}] = \mathbb{E}^0\left[\sup_{g \in \mathcal{G}} \left| \frac{1}{Y} \int_0^Y g(\mathcal{O}_y) dy \right|\right],$$

where

$$\mathcal{G} = \{\eta\gamma'(x + \cdot) - \mu(\eta\gamma'(x + \cdot)) : x \in D \cap \mathbb{Q}\}$$

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Question

Which stability properties are needed to obtain useful quantitative **uniform moment bounds** on **Markovian path integrals** $\int_0^T g(X_t) dt$ for μ -centered functions g ?

Uniform moment bounds

- X stationary \mathcal{X} -valued Borel right Markov process with invariant distribution μ
- X is **exponentially β -mixing**, i.e.,

$$\beta(t) := \int_{\mathcal{X}} \|\mathbb{P}^x(X_t \in \cdot) - \mu\|_{\text{TV}} \mu(dx) \lesssim e^{-\kappa t}, \quad t > 0.$$

- exponential β -mixing is implied by **exponential ergodicity**,

$$\|\mathbb{P}^x(X_t \in \cdot) - \mu\|_{\text{TV}} \lesssim V(x)e^{-\kappa t}, \quad x \in \mathcal{X}, t > 0.$$

- for countable family $\mathcal{G} \subset \mathcal{B}_b(\mathcal{X})$ of μ -centered functions let

$$\mathbb{G}_T(g) := \frac{1}{\sqrt{T}} \int_0^T g(X_s) ds, \quad g \in \mathcal{G}$$

and

$$d_{\mathbb{G}, T}(f, g) := \sqrt{\text{Var}(\mathbb{G}_T(f - g))}$$

Theorem (Dexheimer, Strauch, T. (2022+))

Let X be exp. β -mixing and $m_T \leq T/4$. Then, there exists $\tau \in [m_T, 2m_T]$ such that for any $p \geq 1$,

$$\left(\mathbb{E}^\mu \left[\sup_{g \in \mathcal{G}} |\mathbb{G}_T(g)|^p \right] \right)^{1/p} \leq C_1 \int_0^\infty \log \mathcal{N}(u, \mathcal{G}, \frac{2m_T}{\sqrt{T}} d_\infty) du + C_2 \int_0^\infty \sqrt{\log \mathcal{N}(u, \mathcal{G}, d_{\mathbb{G}, \tau})} du \\ + 4 \sup_{g \in \mathcal{G}} \left(\frac{2m_T}{\sqrt{T}} \|g\|_\infty c_1 p + \|g\|_{\mathbb{G}, \tau} c_2 \sqrt{p} + \frac{1}{2} \|g\|_\infty c_k \sqrt{T} e^{-\frac{\kappa m_T}{p}} \right),$$

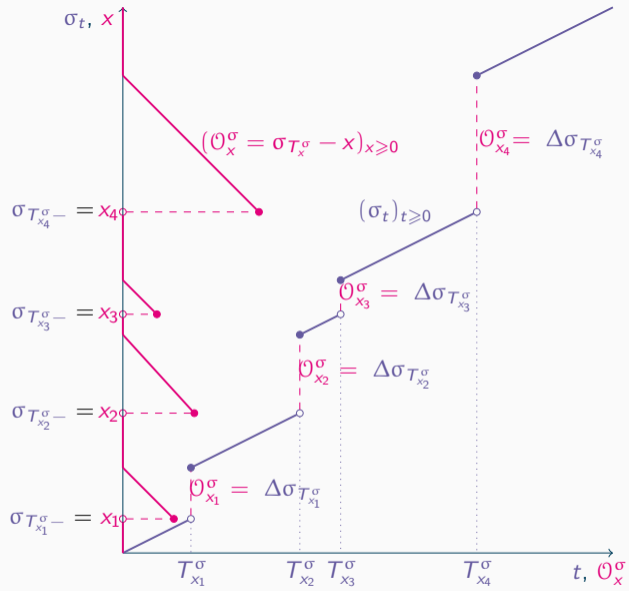
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Consequence

IF \mathcal{O} is exponentially ergodic and γ', γ'' are bounded, then $\mathbb{E}^0 [\|\tilde{f}_Y - f\|_{L^\infty(D)}] \lesssim \frac{1}{\sqrt{Y}}$.



Stability of overshoots

Theorem (Döring, T. (2021+))

Assume that $\mathbb{E}^0[H_1] < \infty$ and either $d_H > 0$ or $\Pi|_{(a,b)} \ll \text{Leb}|_{(a,b)}$ for some interval $(a, b) \subset (0, \infty)$. Then, for any $y \in \mathbb{R}_+$,

$$\lim_{x \rightarrow \infty} \left\| \mathbb{P}^y(\mathcal{O}_x \in \cdot) - \mu \right\|_{\text{TV}} = 0.$$

If additionally for some $\lambda > 0$, $\int_1^\infty e^{\lambda x} \Pi(dx) < \infty$, then for $V_\lambda(x) = \exp(\lambda x)$ and $\alpha > 0$, we have

$$\sup_{y \in \mathbb{R}_+} \frac{\sup_{|f| \leq \alpha \mathcal{U}_\alpha V_\lambda} \left| \mathbb{E}^y[f(\mathcal{O}_x)] - \mu(f) \right|}{\alpha \mathcal{U}_\alpha V_\lambda(y)} \lesssim_\alpha e^{-\kappa(\alpha)x},$$

and for any $\delta \in (0, 1)$,

$$\left\| \mathbb{P}^y(\mathcal{O}_x \in \cdot) - \mu \right\|_{\text{TV}} \lesssim_{(\lambda, \delta)} \mathcal{U}_{2\lambda/\delta} V_\lambda(y) e^{-\frac{\lambda x}{1+\delta}}.$$

Moreover, under the above assumptions, \mathcal{O} is exponentially β -mixing for any initial distribution η such that $\eta(V_\lambda) < \infty$.

Back to data-driven Lévy controls

- Recall: for $f = \mathcal{A}_H \gamma$ and $\tilde{f}_Y(x) = \frac{1}{Y} \int_0^Y \eta \gamma'(x + \mathcal{O}_y) dy$ we have $\mathbb{E}^0[\|\tilde{f}_Y - f\|_{L^\infty(D)}] \lesssim Y^{-1/2}$ in the exponentially ergodic overshoot regime

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- $\mathbb{E}^0[\|\hat{f}_T - f\|_{L^\infty(D)}] \lesssim \frac{1}{\sqrt{\mathbb{E}^0[\xi_1] T}} + \frac{\varepsilon}{\mathbb{E}^0[\xi_1]} + \mathbb{P}^0\left(\left|\frac{\xi_T}{T} - \mathbb{E}^0[\xi_1]\right| > \varepsilon\right)$

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Theorem (Christensen, Strauch, T. (2021+))

Assume $\theta^* \in D$ and let $\hat{\theta}_T = \arg \max_{x \in D} \hat{f}_T(x)$. Given exponentially ergodic overshoots,

$$\mathbb{E}^0[f(\theta^*) - f(\hat{\theta}_T)] \in \mathcal{O}(T^{-1/(2(1+p^{-1})}),$$

provided that $\int_{|x|>1} |x|^p \Pi(dx) < \infty$ for some $p \geq 2$. If Π has an exponential moment, then

$$\mathbb{E}^0[f(\theta^*) - f(\hat{\theta}_T)] \in \mathcal{O}\left(\sqrt{\log T/T}\right).$$

Final Remarks

- no **exploration-exploitation** tradeoff due to **spatial homogeneity** of ξ
- it is an interesting problem to extend results to a high-frequency setting based on **random walk observations** $(\xi_{k\Delta_n})_{k=0,\dots,n}$ for $n\Delta_n \rightarrow \infty$
- For an oscillating Lévy process with ascending/descending ladder height processes H^\pm we have

$$\mathcal{A}^*f = (\mu^+ * \mu^-)'' * f = (\mu^+ * \mu^-) * f'', \quad f \in \mathcal{S}(\mathbb{R})$$

where μ^+ (resp. $\mu^-(-\cdot)$) is the **invariant overshoot measure** of H^+ (resp. H^-) \rightsquigarrow can this be used for convenient constructions of **friendships of Lévy processes**?

Thank you for your attention!